



Existence Result for Nonlinear Degenerated Parabolic Systems

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Abstract: An existence result of a solution for a class of nonlinear parabolic systems is established. The source term is less regular (bounded Radon measure) and no coercivity is made in the non-divergentiel lower order term $\operatorname{div}(c(x, t)|u(x, t)|^{\gamma-2}u(x, t))$. The main contribution of our work is to prove the existence of a renormalized solution without the coercivity condition on the nonlinearities, so we used the Gagliardo-Nirenberg theorem to prove it.

Keywords: *Dirichlet problem; parabolic systems; Gagliardo-Nirenberg inequality; renormalized solutions.*

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1 Introduction

Given a bounded-connected open set Ω of \mathbb{R}^N ($N \geq 2$), with Lipschitz boundary $\partial\Omega$, $Q_T = \Omega \times (0, T)$ is the generic cylinder of an arbitrary finite height, $T < \infty$. We prove the existence of a renormalized solution for the nonlinear parabolic systems

$$\begin{cases} \frac{\partial b_i(x, u_i)}{\partial t} - \operatorname{div}(a(x, t, u_i, \nabla u_i) - \phi_i(x, t, u_i) - F_i) = f_i(x, u_1, u_2) & \text{in } Q_T, \\ u_i(x, t) = 0 & \text{on } \partial\Omega \times (0, T), \\ b_i(x, u_i(x, 0)) = b_i(x, u_{0,i}(x)) & \text{in } \Omega, \end{cases} \quad (1)$$

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where $i = 1, 2$. Here the vector field $a : \Omega \times (0, T) \times \mathbb{R} \times \mathbb{R}^N \rightarrow \mathbb{R}^N$ is a Carathéodory function such that $A(u_i) = -\operatorname{div}\left(a(x, t, u_i, \nabla u_i)\right)$ is a Leray-Lions operator defined on $L^p(0, T; W_0^{1,p}(\nu))$, $\phi_i(x, t, u_i)$ is a Carathéodory function (see assumptions (13)–(14)), and $b_i : \Omega \times \mathbb{R} \rightarrow \mathbb{R}$ is a Carathéodory function such that for every $x \in \Omega$, $b_i(x, \cdot)$ is a strictly increasing C^1 -function, the data $u_{0,i}$ is in $L^1(\Omega)$ such that $b_i(\cdot, u_{0,i})$ in $L^1(\Omega)$. The data $f_i : \Omega \times \mathbb{R} \times \mathbb{R} \rightarrow \mathbb{R}$ is a Carathéodory function (see assumptions H4) and $F_i \in (L^{p'}(\nu))^N$. When problem (1) is investigated, there is a difficulty due to the fact that the data $b_1(x, u_0^1(x))$ and $b_2(x, u_0^2(x))$ only belong to L^1 and the functions $\left(a(x, t, u_i, \nabla u_i)\right)$, $\phi_i(x, t, u_i)$ and $f_i(x, u_1, u_2)$ do not belong to $(L_{loc}^1(Q_T))^N$ in general, so that proving existence of weak solution seems to be an arduous task, and we cannot use the Stocks formula in the a priori estimates of the nonlinearity $\phi_i(x, t, u_i)$. In order to overcome this difficulty, we work with the framework of renormalized solutions (see Definition 3.1). The notion of renormalized solutions was introduced by R.-J. DiPerna and P.-L. Lions [8] for the study of the Boltzmann equation. It was adapted to the study of some nonlinear elliptic or parabolic problems in fluid mechanics, see [6]. In the case where $b(x, u) = u$, the existence of renormalized solutions for (1) has been established by R.-Di Nardo [5]. In the case where $\phi(x; t; u) = 0$ and $f \in L^1(Q_T)$, the existence of renormalized solutions has been established by H. Redwane [13] in the classical Sobolev space, the existence results are already proved by the authors in the case where $f_i(x, u_1, u_2)$ is replaced by $f - \operatorname{div}(g)$, where $f \in L^1(Q_T)$ and $g \in (L^{p'}(Q_T))^N$. For the elliptic version of (1) we refer to [10].

One of the models of applications of these operators is the system of Boussinesq:

$$\frac{\partial u}{\partial t} + (u \cdot \nabla)u - 2\operatorname{div}(\mu(\theta)\varepsilon(u)) + \nabla p = F(\theta) \quad \text{in } Q_T,$$

$$\frac{\partial b(\theta)}{\partial t} + u \cdot \nabla b(\theta) - \Delta \theta = 2\mu(\theta)|\varepsilon(u)|^2 \quad \text{in } Q_T,$$

$$u(t=0) = u_0, \quad b(\theta)(t=0) = b(\theta_0) \quad \text{on } \Omega,$$

$$u = 0 \quad \theta = 0 \quad \text{on } \partial\Omega \times (0, T).$$

The first equation is the motion conservation equation, the unknowns are the fields of displacement $u : Q_T \rightarrow \mathbb{R}^N$ and temperature $\theta : Q_T \rightarrow \mathbb{R}$. The field $\varepsilon(u) = \frac{1}{2}(\nabla u + (\nabla u)^t)$ is the strain rate tensor.

It is our purpose, in this paper to generalize the result of [2, 5, 13] and we prove the existence of a renormalized solution of system (1).

The plan of the paper is as follows: In Section 2 we give basic assumptions. In Section 3 we give the definition of a renormalized solution of (1), and we establish (Theorem 3.1) the existence of such a solution.

2 Preliminaries and Auxiliary Results

We recall here some standard notations, properties and results which will be used throughout the paper.

Let Ω be a bounded open set of \mathbb{R}^N and $Q_T = \Omega \times (0, T)$, T is a positive real number. Let $\nu(x)$ be a nonnegative function on Ω such that $\nu(x) \in L^r(\Omega)$, $r \geq 1$, $\nu(x)^{-1} \in L^t(\Omega)$,

$p \geq 1 + 1/t$. We denote by $L^p(\Omega, \nu)$, or simply $L^p(\nu)$ if there is no confusion, $p \geq 1$, the space of measurable functions u on Ω such that

$$\|u\|_{L^p(\nu)} = \left(\int_{\Omega} |u|^p \nu(x) dx \right)^{\frac{1}{p}} < +\infty, \tag{2}$$

and by $W^{1,p}(\nu)$ the completion of the space $C^1(\overline{\Omega})$ with respect to the norm

$$\|u\|_{W^{1,p}(\nu)} = \|u\|_{L^p(\nu)} + \|\nabla u\|_{L^p(\nu)}. \tag{3}$$

Moreover, we denote by $W_0^{1,p}(\nu)$ the closure of $C_0^1(\overline{\Omega})$ in $W^{1,p}(\nu)$, provided with the induced topology defined by the induced norm, and by $W^{-1,p'}(\nu^{1-p'})$, $p' = \frac{p}{p-1}$, its dual space. $W^{1,p}(\nu)$ and $W_0^{1,p}(\nu)$ are reflexive Banach spaces if $1 < p < \infty$, (see [11]).

Denote $V = W_0^{1,p}(\nu)$, $H = L^2(\nu)$ and $V^* = W_0^{-1,p'}(\nu^{1-p'})$, with $p \geq 2$. The dual space of $X := L^p(0, T; W_0^{1,p}(\nu))$ denoted X^* is identified with $L^{p'}(0, T; V^*)$. Define $W_p^1(0, T, V, H) = \{v \in X : v' \in X^*\}$. Endowed with the norm

$$\|u\|_{W_p^1} = \|u\|_X + \|u'\|_{X^*},$$

$W_p^1(0, T, V, H)$ is a Banach space. Here u' stands for the generalized time derivative of u , that is,

$$\int_0^T u'(t)\varphi(t)dt = - \int_0^T u(t)\varphi'(t)dt \text{ for all } \varphi \in C_0^\infty(0, T).$$

Lemma 2.1 [14]

1. The evolution triple $V \hookrightarrow H \hookrightarrow V^*$ is verified.
2. The imbedding $W_p^1(0, T, V, H) \hookrightarrow C(0, T, H)$ is continuous.
3. The imbedding $W_p^1(0, T, V, H) \hookrightarrow L^p(Q_T, \nu)$ is compact.

Lemma 2.2 [1] Let $\{v_n\}$ be a bounded sequence in $L^p(0, T; V)$ such that

$$\frac{\partial v_n}{\partial t} = \alpha_n + \beta_n \text{ in } \mathcal{D}'(Q_T)$$

with $\{\alpha_n\}$ and $\{\beta_n\}$ being two bounded sequences respectively in X^* and in $L^1(Q_T)$. Then $v_n \rightarrow v$ in $L_{loc}^p(Q_T, \nu)$. Furthermore, $v_n \rightarrow v$ strongly in $L^1(Q_T)$.

From now on, we assume that the following assumptions hold true

$$\nu(x)^{-1} \in L^t(\Omega), \quad t \geq \frac{N}{p}, \quad 1 + \frac{1}{t} < p < N(1 + \frac{1}{t}), \tag{4}$$

$$\nu(x) \in L^r(\Omega), \quad r > \frac{Nt}{pt - N}. \tag{5}$$

An important tool that we will use here, is the following weighted version of the Sobolev inequality (see Theorem 3.1 and Corollary 3.5 in [11]).

Proposition 2.1 [11] Assume that (4) and (5) hold true. Let \tilde{p} denote the number associated with p defined by

$$\frac{1}{\tilde{p}} = r' \left(\frac{1}{p} \left(1 + \frac{1}{t} \right) - \frac{1}{N} \right).$$

Then the imbedding of $W_0^{1,p}(\nu)$ into $L^{\tilde{p}}(\nu)$ is continuous. moreover, there exists a constant $C_0 > 0$ depending on N, p, ν, t , such that

$$\|u\|_{L^{\tilde{p}}(\nu)} \leq C_0 \|\nabla u\|_{L^p(\nu)}, \forall u \in W_0^{1,p}(\nu). \quad (6)$$

Using this proposition, we can prove the following interpolation result.

Proposition 2.2 Assume that (4) and (5) hold true. Let v be a function in $W_0^{1,p}(\nu) \cap L^s(\Omega)$ with $2 \leq p < N$ and $s > r'$. Then there exists a positive constant C , depending on N, p, ν, t and q , such that

$$\|v\|_{L^\sigma(\nu)} \leq C \|\nabla v\|_{L^p(\nu)}^{1-\theta} \|v\|_{L^s(\Omega)}^\theta$$

for every θ and σ satisfying

$$0 \leq \theta \leq 1, 1 \leq \sigma \leq +\infty, \frac{1}{\sigma} = \theta + r'(1-\theta) \left(\left(1 + \frac{1}{t} \right) \frac{1}{p} - \frac{1}{N} \right), r > \frac{Nt}{pt-N}.$$

Proof. For every $1 \leq \sigma \leq \tilde{p}$, we can write $\frac{1}{\sigma} = \theta + \frac{1-\theta}{\tilde{p}}$ for some $0 \leq \theta \leq 1$. then by the Hölder inequality and (6), one has

$$\|v\|_{L^\sigma(\nu)} \leq C_0 \|\nabla v\|_{L^p(\nu)}^{1-\theta} \|v\|_{L^1(\nu)}^\theta \leq C_0 \|\nabla v\|_{L^p(\nu)}^{1-\theta} \|\nu\|_{L^{s'}(\Omega)}^\theta \|v\|_{L^s(\Omega)}^\theta,$$

which gives the desired result.

As an immediate consequence of the previous result, we get

Corollary 2.1 Let $v \in L^p((0, T), W_0^{1,p}(\nu)) \cap L^\infty((0, T), L^s(\Omega))$, with $2 \leq p < N$ and $s > r'$. Then $v \in L^\sigma(\nu)$ with $\sigma = \frac{\tilde{p}p + \tilde{p} - p}{\tilde{p}}$. Moreover,

$$\int_{Q_T} \nu(x) |v|^\sigma dx dt \leq C \|v\|_{L^\infty(0, T, L^s(\Omega))}^{\frac{\tilde{p}-p}{\tilde{p}}} \int_{Q_T} \nu(x) |\nabla v|^p dx dt.$$

Proof. By virtue of Proposition 2.2, we can write

$$\int_{\Omega} \nu(x) |v|^\sigma dx \leq C \|\nabla v\|_{L^p(\nu)}^{(1-\theta)\sigma} \|v\|_{L^s(\Omega)}^{\theta\sigma}.$$

Integrating between 0 and T , we get

$$\int_0^T \int_{\Omega} \nu(x) |v|^\sigma dx dt \leq C \int_0^T \|\nabla v\|_{L^p(\nu)}^{(1-\theta)\sigma} \|v\|_{L^s(\Omega)}^{\theta\sigma} dt. \quad (7)$$

Since $v \in L^p((0, T), W_0^{1,p}(\nu)) \cap L^\infty((0, T), L^s(\Omega))$, we have

$$\int_0^T \int_{\Omega} \nu(x) |v|^\sigma dx dt \leq C \|v\|_{L^\infty(0, T, L^s(\Omega))}^{\theta\sigma} \int_0^T \|\nabla v(t)\|_{L^p(\nu)}^{(1-\theta)\sigma} dt.$$

Now we choose θ such that $(1 - \theta)\sigma = p$ and $\theta\sigma = \frac{\tilde{p}-p}{\tilde{p}}$. This choice yields

$$\theta = \frac{\tilde{p} - p}{p\tilde{p} + \tilde{p} - p}, \quad \sigma = \frac{p\tilde{p} + \tilde{p} - p}{\tilde{p}}.$$

Then, (7) becomes

$$\int_0^T \int_{\Omega} \nu(x)|v|^\sigma dxdt \leq C \|v\|_{L^\infty(0,T,L^s(\Omega))}^{\frac{\tilde{p}-p}{\tilde{p}}} \int_0^T \|\|\nabla v(t)\|\|_{L^p(\nu)}^p dt.$$

3 Assumptions on Data

Let Ω be a bounded open set of \mathbb{R}^N ($N \geq 2$), T be a positive real number, and $Q_T = \Omega \times (0, T)$.

3.1 Assumptions

Throughout this paper, we assume that the following assumptions hold true:

Assumptions (H1)

$$b_i : \Omega \times \mathbb{R} \rightarrow \mathbb{R} \text{ is a Carathéodory function such that for every } x \in \Omega, \quad (8)$$

$b_i(x, \cdot)$ is a strictly increasing $\mathcal{C}^1(\mathbb{R})$ -function with $b_i(x, 0) = 0$, for any $k > 0$, there exist a constant $\lambda_i > 0$ and functions $A_k^i \in L^\infty(\Omega)$ and $B_k^i \in L^p(\Omega)$ such that: for almost every x in Ω

$$\lambda_i \leq \frac{\partial b_i(x, s)}{\partial s} \leq A_k^i(x) \quad \text{and} \quad \left| \nabla_x \left(\frac{\partial b_i(x, s)}{\partial s} \right) \right| \leq B_k^i(x) \quad \forall |s| \leq k. \quad (9)$$

Assumptions (H2) Let $a : Q_T \times \mathbb{R} \times \mathbb{R}^N \rightarrow \mathbb{R}^N$ be a Carathéodory function such that, for any $k > 0$, there exist ν_k and a function $h_k \in L^p(\nu)$ with

$$|a(x, t, s, \xi)| \leq \nu(x) \left(h_k(x, t) + |\xi|^{p-1} \right) \quad \forall |s| \leq k, \quad (10)$$

$$a(x, t, s, \xi)\xi \geq \alpha \nu(x) |\xi|^p \quad \text{with } \alpha > 0, \quad (11)$$

$$(a(x, t, s, \xi) - a(x, t, s, \eta))(\xi - \eta) > 0 \quad \text{with } \xi \neq \eta. \quad (12)$$

Assumptions (H3) Let $\phi_i : Q_T \times \mathbb{R} \rightarrow \mathbb{R}^N$ be a Carathéodory function such that

$$|\phi_i(x, t, s)| \leq c_i(x, t) |s|^\gamma \nu(x), \quad (13)$$

$$c_i(x, t) \in L^\tau(\nu) \quad \text{with} \quad \tau = \frac{p(3\tilde{p} - p)}{(p - 1)(\tilde{p} - p)}, \quad \gamma = \frac{2(p - 1)(p\tilde{p} + \tilde{p} - p)}{p(3\tilde{p} - p)} \quad (14)$$

for almost every $(x, t) \in Q_T$, for every $s \in \mathbb{R}$ and every $\xi, \eta \in \mathbb{R}^N$.

Assumptions (H4) We suppose for that for $i=1,2$ $f_i : \Omega \times \mathbb{R} \times \mathbb{R} \rightarrow \mathbb{R}$ is a Carathéodory function with $f_1(x, 0, s) = f_2(x, s, 0) = 0$ a.e $x \in \Omega$, $\forall s \in \mathbb{R}$. And for almost every $x \in \Omega$, for every $s_1, s_2 \in \mathbb{R}$

$$\text{signe}(s_i) f_i(x, s_1, s_2) \geq 0. \quad (15)$$

The growth assumptions on f_i are as follows: for each $k > 0$ there exist $\sigma_k > 0$ and a function F_k in $L^1(\Omega)$ such that

$$|f_1(x, s_1, s_2)| \leq F_k + \sigma_k |b_2(x, s_2)|. \quad \text{a.e } x \in \Omega, \forall |s_1| \leq k, \quad \forall s_2 \in \mathbb{R}. \quad (16)$$

for each $k > 0$ there exist $\mu_k > 0$ and a function G_k in $L^1(\Omega)$ such that

$$|f_2(x, s_1, s_2)| \leq G_k(x) + \mu_k |b_1(x, s_1)|. \quad \text{a.e } x \in \Omega, \forall |s_2| \leq k, \quad \forall s_1 \in \mathbb{R}. \quad (17)$$

$u_{0,i}$ is a measurable function such that $b_i(x, u_{0,i}) \in L^1(\Omega)$ for $i = 1, 2$.

4 Main Results

In this section, we study the existence of renormalized solutions to systems (1).

Definition 4.1 A couple of measurable functions (u_1, u_2) defined on Q_T is called a *renormalized* solution of (1) if for $i=1,2$. the function u_i satisfies

$$b_i(x, u_i) \in L^\infty(0, T; L^1(\Omega)), \quad (18)$$

$$T_k(u_i) \in L^p(0, T; W_0^{1,p}(\nu)) \text{ for any } k > 0, \quad (19)$$

$$\lim_{m \rightarrow +\infty} \frac{1}{m} \int_{\{(x,t) \in Q_T: |u_i(x,t)| \leq m\}} a(x, t, u_i, \nabla u_i) \nabla u_i \, dx \, dt = 0, \quad (20)$$

and if for every function S in $W^{2,\infty}(\mathbb{R})$ which is piecewise C^1 and such that S' has a compact support

$$\begin{aligned} & \frac{\partial B_{i,S}(x, u_i)}{\partial t} - \operatorname{div} \left(a(x, t, u_i, \nabla u_i) S'(u_i) \right) + S''(u_i) a(x, t, u_i, \nabla u_i) \nabla u_i \\ & + \operatorname{div} \left(\phi_i(x, t, u_i) S'(u_i) \right) - S''(u_i) \phi_i(x, t, u_i) \nabla u_i \\ & = f_i(x, u_1, u_2) S'(u_i) - \operatorname{div} (S'(u_i) F_i) + S''(u_i) F_i \nabla u_i \text{ in } D'(Q_T), \end{aligned} \quad (21)$$

and

$$B_{i,S}(x, u_i)(t = 0) = B_{i,S}(x, u_{i,0}) \quad \text{in } \Omega, \quad (22)$$

where $B_{i,S}(x, z) = \int_0^z \frac{\partial b_i(x, s)}{\partial s} S'(s) ds$.

Equation (21) is formally obtained through pointwise multiplication of equation (1) by $S'(u)$. However meanwhile $a(x, t, u_i, \nabla u_i)$ and $\phi_i(x, t, u_i)$ do not in general make sense in (1). Recall that for a renormalized solution, due to (19), each term in (21) has a meaning in $L^1(Q_T) + L^{p'}(0, T; W^{-1,p'}(\nu^{1-p'}))$ (see e.g. [6]). We have

$$\frac{\partial B_{i,S}(x, u_i)}{\partial t} \text{ belongs to } L^{p'}(0, T; W^{-1,p'}(\nu^{1-p'})) + L^1(Q_T). \quad (23)$$

$$B_{i,S}(x, u_i) \text{ belongs to } L^p(0, T; W_0^{1,p}(\nu)). \quad (24)$$

Then (23) and (24) imply that $B_{i,S}(x, u_i)$ belongs to $C^0([0, T]; L^1(\Omega))$ (for the proof of this trace result see [12],) so that the initial condition (22) makes sense.

Theorem 4.1 *Let $b(x, u_0) \in L^1(\Omega)$, assume that (H1)-(H4) hold true, then there exists at least a renormalized solution (u_1, u_2) of problem (1) in the sense of Definition (4.1).*

Proof. Step 1. Let us introduce the following regularization of the data: for $i=1,2$. For each $n > 0$

$$b_{i,n}(x, r) = b(x, T_n(r)) + \frac{r}{n} \quad \forall r \in \mathbb{R}, \tag{25}$$

$$a_n(x, t, s, \xi) = a(x, t, T_n(s), \xi) \quad \text{a.e. } (x, t) \in Q_T, \quad \forall s \in \mathbb{R}, \quad \forall \xi \in \mathbb{R}^N, \tag{26}$$

$$\phi_{i,n}(x, t, r) = \phi_i(x, t, T_n(r)) \quad \text{a.e. } (x, t) \in Q_T, \quad \forall r \in \mathbb{R}. \tag{27}$$

Let $f_{1,n}(x, s_1, s_2) = f_1(x, T_n(s_1), T_n(s_2))$ a.e $x \in \Omega, \forall s_1, s_2 \in \mathbb{R}$.

$$\text{and } f_{2,n}(x, s_1, s_2) = f_2(x, T_n(s_1), T_n(s_2)) \quad \text{a.e } x \in \Omega, \forall s_1, s_2 \in \mathbb{R}. \tag{28}$$

Let $u_{i,0n} \in C_0^\infty(\Omega)$ such that

$$b_{i,n}(x, u_{i,0n}) \rightarrow b_i(x, u_{i,0}) \text{ strongly in } L^1(\Omega). \tag{29}$$

In view of (25), for $i=1,2$ $b_{i,n}$ is a Carathéodory function and satisfies (9), there exists $\lambda_i > 0$ such that:

$$\lambda_i + \frac{1}{n} \leq \frac{\partial b_{i,n}(x, s)}{\partial s} \text{ and } |b_{i,n}(x, s)| \leq \max_{|s| \leq n} |b_i(x, s)| \quad \text{a.e. } x \in \Omega, \quad \forall s \in \mathbb{R}.$$

Let us now consider the regularized problem

$$\begin{cases} \frac{\partial b_{i,n}(x, u_{i,n})}{\partial t} - \text{div}(a_n(x, t, u_{i,n}, \nabla u_{i,n}) - \phi_{i,n}(x, t, u_{i,n}) - F_i) = f_{i,n}(x, u_1, u_2) \text{ in } Q_T, \\ u_{i,n}(x, t) = 0 \text{ on } \partial\Omega \times (0, T), \\ b_{i,n}(x, u_{i,n})(t = 0) = b_{i,n}(x, u_{i,0n}) \text{ in } \Omega. \end{cases} \tag{30}$$

In view of (16)-(17), there exist $F_{1,n} \in L^1(\Omega)$ and $F_{2,n} \in L^1(\Omega)$ and $\sigma_n > 0, \mu_n > 0$ such that :

$$|f_{1,n}(x, s_1, s_2)| \leq F_{1,n}(x) + \sigma_n \max_{|s| \leq n} |b_i(x, s)|. \quad \text{a.e } x \in \Omega, \quad \forall s_1, s_2 \in \mathbb{R}.$$

$$|f_{2,n}(x, s_1, s_2)| \leq F_{2,n}(x) + \mu_n \max_{|s| \leq n} |b_i(x, s)|. \quad \text{a.e } x \in \Omega, \quad \forall s_1, s_2 \in \mathbb{R}.$$

As a consequence, proving the existence of weak solution $u_{i,n} \in L^p(0, T; W_0^{1,p}(\nu))$ of (30) is an easy task (see e.g. [?, 9]).

Step 2: The estimates derived in this step rely on standard techniques for problems of type (30). So we just sketch the proof of them (the reader is referred to [4]) for the elliptic version. Let $\tau_1 \in (0, T)$ and t be fixed in $(0, \tau_1)$. For $i=1,2$, using $T_k(u_{i,n})\chi_{(0,t)}$ as a test function in (30), we integrate between $(0, \tau_1)$, and by the condition (13) we have

$$\begin{aligned} & \int_{\Omega} B_{i,k}^n(x, u_{i,n}(t)) dx + \int_{Q_t} a_n(x, t, u_{i,n}, \nabla u_{i,n}) \nabla T_k(u_{i,n}) dx ds \\ & \leq \int_{Q_t} c(x, t) |u_{i,n}|^{\gamma} \nu(x) |\nabla T_k(u_{i,n})| dx ds + \int_{Q_t} f_{i,n}(x, u_1^n, u_2^n) T_k(u_{i,n}) dx ds \end{aligned} \tag{31}$$

$$+ \int_{\Omega} B_k^{i,n}(x, u_{i,0}^n) dx + \int_{Q_t} F_i \nabla T_k(u_i^n) dx ds,$$

where $B_{i,k}^n(x, r) = \int_0^r T_k(s) \frac{\partial b_{i,n}(x, s)}{\partial s} ds$. Due to definition of $B_{i,k}^n$ we have:

$$0 \leq \int_{\Omega} B_{i,k}^n(x, u_{i,0n}) dx \leq k \int_{\Omega} |b_{i,n}(x, u_{i,0n})| dx = k \|b_i(x, u_{i,0n})\|_{L^1(\Omega)} \quad \forall k > 0. \quad (32)$$

Using (31), (11) and (28) we obtain:

$$\begin{aligned} \int_{\Omega} B_{i,k}^n(x, u_{i,n}(t)) dx + \alpha \int_{Q_t} \nu(x) |\nabla T_k(u_{i,n})|^p dx ds &\leq \int_{Q_t} c(x, t) |u_{i,n}|^\gamma \nu(x) |\nabla T_k(u_{i,\epsilon})| ds dx \\ &+ k (\|b_i(x, u_{i,0n})\|_{L^1(\Omega)} + \|f_{i,n}\|_{L^1(Q_T)}) + \int_{Q_t} F_i \nabla T_k(u_{i,n}) dx ds. \end{aligned} \quad (33)$$

Let $M_i = \left(\sup_n \|f_{i,n}\|_{L^1(Q_T)} + \|b_i(x, u_{i,0n})\|_{L^1(\Omega)} \right)$. Noting that

$$B_{i,k}^n(x, s) = \int_0^s T_k(\sigma) \frac{\partial b_{i,n}(x, \sigma)}{\partial \sigma} d\sigma \geq \frac{\lambda_i + \frac{1}{n}}{2} |T_k(s)|^2 > \frac{\lambda_i}{2} |T_k(s)|^2$$

we deduce from (31) and (32) that

$$\begin{aligned} &\frac{\lambda_i}{2} \int_{\Omega} |T_k(u_{i,n})|^2 dx + \alpha \int_{Q_t} \nu(x) |\nabla T_k(u_{i,n})|^p dx ds \\ &\leq M_i k + \int_{Q_t} c_i(x, t) |u_{i,n}|^\gamma \nu(x) |\nabla T_k(u_{i,n})| dx ds + \int_{Q_t} F_i \nabla T_k(u_{i,n}) dx ds. \end{aligned} \quad (34)$$

By Gagliardo-Nirenberg and Young inequalities we have:

$$\begin{aligned} &\int_{Q_t} c_i(x, t) |u_{i,n}|^\gamma \nu(x) |\nabla T_k(u_{i,n})| dx ds \\ &\leq C_i \frac{\gamma(\tilde{p}-p)}{2(p\tilde{p} + \tilde{p}-p)} \|c_i(x, t)\|_{L^\tau(Q_{\tau_1}, \nu)} \sup_{t \in (0, \tau_1)} \int_{\Omega} |T_k(u_{i,n})|^2 dx \\ &\quad + C_i \frac{2p\tilde{p} + (2-\gamma)(\tilde{p}-p)}{2(p\tilde{p} + \tilde{p}-p)} \|c_i(x, t)\|_{L^\tau(Q_{\tau_1}, \nu)} \\ &\quad \left(\int_{Q_{\tau_1}} \nu(x) |\nabla T_k(u_{i,n})|^p dx ds \right)^{\left(\frac{1}{p} + \frac{\gamma\tilde{p}}{p\tilde{p} + \tilde{p}-p}\right) \frac{2(p\tilde{p} + \tilde{p}-p)}{2p\tilde{p} + (2-\gamma)(\tilde{p}-p)}}. \end{aligned} \quad (35)$$

Since $\gamma = \frac{2(p-1)(p\tilde{p} + \tilde{p}-p)}{p(3\tilde{p}-p)}$ and by using (34) and (35), we obtain

$$\begin{aligned} &\frac{\lambda_i}{2} \int_{\Omega} |T_k(u_{i,n})|^2 dx + \alpha \int_{Q_t} \nu(x) |\nabla T_k(u_{i,n})|^p dx ds \leq M_i k + \\ &C_i \frac{\gamma(\tilde{p}-p)}{2(p\tilde{p} + \tilde{p}-p)} \|c_i(x, t)\|_{L^\tau(Q_{\tau_1}, \nu)} \sup_{t \in (0, \tau_1)} \int_{\Omega} |T_k(u_{i,n})|^2 dx + \frac{\alpha^{-\frac{p'}{p}}}{p'} \|F_i\|_{(L^{p'}(\nu))^N} \end{aligned}$$

$$\begin{aligned}
 &+C_i \frac{2p\tilde{p} + (2 - \gamma)(\tilde{p} - p)}{2(p\tilde{p} + \tilde{p} - p)} \|c_i(x, t)\|_{L^\tau(Q_{\tau_1}, \nu)} \int_{Q_{\tau_1}} \nu(x) |\nabla T_k(u_{i,n})|^p dx ds \\
 &\quad + \frac{\alpha}{p} \int_{Q_t} \nu(x) |\nabla T_k(u_{i,n})|^p dx ds
 \end{aligned}$$

which is equivalent to

$$\begin{aligned}
 &\left(\frac{\lambda_i}{2} - C_i \frac{\gamma(\tilde{p} - p)}{2(p\tilde{p} + \tilde{p} - p)} \|c_i(x, t)\|_{L^\tau(Q_{\tau_1}, \nu)}\right) \sup_{t \in (0, \tau_1)} \int_{\Omega} |T_k(u_{i,n})|^2 dx \\
 &\quad + \alpha \int_{Q_{\tau_1}} \nu(x) |\nabla T_k(u_{i,n})|^p dx ds \\
 &- \left(C_i \frac{2p\tilde{p} + (2 - \gamma)(\tilde{p} - p)}{2(p\tilde{p} + \tilde{p} - p)} \|c_i(x, t)\|_{L^\tau(Q_{\tau_1}, \nu)} + \frac{\alpha}{p}\right) \int_{Q_{\tau_1}} \nu(x) |\nabla T_k(u_{i,n})|^p dx ds \leq M_i k.
 \end{aligned}$$

If we choose τ_1 such that

$$\left(\frac{\lambda_i}{2} - C_i \frac{\gamma(\tilde{p} - p)}{2(p\tilde{p} + \tilde{p} - p)} \|c_i(x, t)\|_{L^\tau(Q_{\tau_1}, \nu)}\right) > 0, \tag{36}$$

$$\left(\frac{\alpha}{p'} - C_i \frac{2p\tilde{p} + (2 - \gamma)(\tilde{p} - p)}{2(p\tilde{p} + \tilde{p} - p)} \|c_i(x, t)\|_{L^\tau(Q_{\tau_1}, \nu)}\right) > 0, \tag{37}$$

and then denote by C_i the minimum between the constants $\left(\frac{\lambda_i(p\tilde{p} + \tilde{p} - p)}{\gamma(\tilde{p} - p) \|c_i(x, t)\|_{L^\tau(Q_{\tau_1}, \nu)}}\right)$ and $\left(\frac{2\alpha(p\tilde{p} + \tilde{p} - p)}{p'[2p\tilde{p} + (2 - \gamma)(\tilde{p} - p)] \|c_i(x, t)\|_{L^\tau(Q_{\tau_1}, \nu)}}\right)$, we obtain

$$\sup_{t \in (0, \tau_1)} \int_{\Omega} |T_k(u_{i,n})|^2 dx + \int_{Q_{\tau_1}} \nu(x) |\nabla T_k(u_{i,n})|^p dx dt \leq C_i M_i k. \tag{38}$$

Then, by (38) and Lemma 3.1([?, 2]), we conclude that $T_k(u_{i,n})$ is bounded in $L^p(0, T, W_0^{1,p}(\nu))$ independently of n and for any $k \geq 0$, so there exists a subsequence still denoted by $u_{i,n}$ such that

$$T_k(u_{i,n}) \rightharpoonup H_{i,k} \text{ weakly in } L^p(0, T, W_0^{1,p}(\nu)). \tag{39}$$

Lemma 4.1 (see [2])

$$u_{i,n} \rightarrow u_i \text{ a.e. } Q_T, \quad b_i(x, u_i) \in L^\infty(0, T; L^1(\Omega)), \tag{40}$$

where u_i is a measurable function defined on Q_T for $i=1,2$.

$$\lim_{m \rightarrow +\infty} \limsup_{n \rightarrow +\infty} \frac{1}{m} \int_{\{|u_{i,n}| \leq m\}} a(x, t, u_{i,n}, \nabla u_{i,n}) \nabla u_{i,n} dx dt = 0. \tag{41}$$

Step 4: In this step we prove that the weak limit $X_{i,k}$ of $a(x, t, T_k(u_{i,n}) \nabla T_k(u_{i,n}))$ can be identified with $a(x, t, T_k(u_i), \nabla T_k(u_i))$, for $i=1,2$. In order to prove this result we recall the following lemma.

Lemma 4.2 For $i=1,2$, the subsequence of $u_{i,n}$ satisfies for any $k \geq 0$:

$$\limsup_{n \rightarrow +\infty} \int_{Q_T} \int_0^t a(x, s, u_{i,n}, \nabla T_k(u_{i,n})) \nabla T_k(u_{i,n}) ds dx dt \leq \int_{Q_T} \int_0^t X_{i,k} \nabla T_k(u_i) dx ds dt, \quad (42)$$

$$\lim_{n \rightarrow +\infty} \int_{Q_T} \int_0^t \left(a(x, t, T_k(u_{i,n}), \nabla T_k(u_{i,n})) - a(x, t, T_k(u_i), \nabla T_k(u_i)) \right) \left(\nabla T_k(u_{i,n}) - \nabla T_k(u_i) \right) = 0, \quad (43)$$

$$X_{i,k} = a(x, t, T_k(u_i), \nabla T_k(u_i)) \quad \text{a.e. in } Q_T, \quad (44)$$

and as n tends to $+\infty$

$$a(x, t, T_k(u_{i,n}), \nabla T_k(u_{i,n})) \nabla T_k(u_{i,n}) \rightharpoonup a(x, t, T_k(u_i), \nabla T_k(u_i)) \nabla T_k(u_i) \quad (45)$$

weakly in $L^1(Q_T)$.

For $i=1,2$. We introduce a time regularization of the $T_k(u_i)$ for $k > 0$ in order to perform the monotonicity method.

Lemma 4.3 (see H. Redwane [13]) Let $k \geq 0$ be fixed. Let S be an increasing $C^\infty(\mathbb{R})$ -function such that $S(r) = r$ for $|r| \leq k$, and $\text{supp} S'$ is compact. Then

$$\liminf_{\mu \rightarrow +\infty} \lim_{n \rightarrow +\infty} \int_0^T \int_0^t \left\langle \frac{\partial b_{i,n}(x, u_{i,n})}{\partial t}, S'(u_{i,n})(T_k(u_{i,n}) - (T_k(u_i))_\mu) \right\rangle \geq 0,$$

where $\langle \cdot, \cdot \rangle$ denotes the duality pairing between $L^1(\Omega) + W^{-1,p'}(\nu^{1-p'})$ and $L^\infty(\Omega) \cap W_0^{1,p}(\nu)$.

Let S_m be a sequence of increasing C^∞ -function such that:

$$S_m(r) = r \text{ for } |r| \leq m, \text{ supp}(S'_m) \subset [-2m, 2m] \text{ and } \|S''_m\|_{L^\infty(\mathbb{R})} \leq \frac{3}{m} \text{ for any } m \geq 1.$$

For $i=1,2$. We use the sequence $(T_k(u_i))_\mu$ of approximation of $T_k(u_i)$, and plug the test function $S'_m(u_{i,n})(T_k(u_{i,n}) - (T_k(u_i))_\mu)$ for $m > 0$ and $\mu > 0$. For fixed $k \geq 0$, let $W_\mu^n = T_k(u_{i,n}) - (T_k(u_i))_\mu$. We obtain upon integration over $(0, t)$ and then over $(0, T)$:

$$\begin{aligned} & \int_0^T \int_0^t \left\langle \frac{\partial b_{i,n}(x, u_{i,n})}{\partial t}, S'_m(u_{i,n}) W_\mu^n \right\rangle ds dt \\ & + \int_{Q_T} \int_0^t a_n(x, s, u_{i,n}, \nabla u_{i,n}) S'_m(u_{i,n}) \nabla W_\mu^n ds dt dx \\ & + \int_{Q_T} \int_0^t a_n(x, s, u_{i,n}, \nabla u_{i,n}) S''_m(u_{i,n}) \nabla u_{i,n} \nabla W_\mu^n ds dt dx \\ & - \int_{Q_T} \int_0^t \phi_{i,n}(x, s, u_{i,n}) S'_m(u_{i,n}) \nabla W_\mu^n ds dt dx \\ & - \int_{Q_T} \int_0^t S''_m(u_{i,n}) \phi_{i,n}(x, s, u_{i,n}) \nabla u_{i,n} \nabla W_\mu^n ds dt dx = \int_{Q_T} \int_0^t f_{i,n} S'_m(u_{i,n}) W_\mu^n dx ds dt \end{aligned} \quad (46)$$

$$+ \int_{Q_T} \int_0^t F_i S'_m(u_{i,n}) \nabla W_\mu^n \, ds \, dt \, dx + \int_{Q_T} \int_0^t F_i S''_m(u_{i,n}) \nabla u_{i,n} \nabla W_\mu^n \, ds \, dt \, dx.$$

We pass to the limit in (46) as $n \rightarrow +\infty$, $\mu \rightarrow +\infty$ and then $m \rightarrow +\infty$ for k being a fixed real number. We use Lemma (4.3) and proceed as in ([4,13]), then it possible to conclude that

$$\liminf_{\mu \rightarrow +\infty} \lim_{n \rightarrow +\infty} \int_0^T \int_0^t \left\langle \frac{\partial b_{i,n}(x, u_{i,n})}{\partial t}, W_\mu^n \right\rangle \, ds \, dt \geq 0 \quad \text{for any } m \geq k, \tag{47}$$

$$\lim_{m \rightarrow +\infty} \limsup_{\mu \rightarrow +\infty} \limsup_{n \rightarrow +\infty} \int_{Q_T} \int_0^t a_n(x, t, u_{i,n}, \nabla u_{i,n}) S''_m(u_{i,n}) \nabla u_{i,n} \nabla W_\mu^n \, ds \, dt \, dx = 0, \tag{48}$$

$$\lim_{\mu \rightarrow +\infty} \lim_{n \rightarrow +\infty} \int_{Q_T} \int_0^t f_{i,n} S'_m(u_{i,n}) W_\mu^n \, ds \, dt \, dx = 0, \tag{49}$$

$$\lim_{\mu \rightarrow +\infty} \int_{Q_T} \int_0^t F_i S'_m(u_{i,n}) \nabla W_\mu^n \, ds \, dt \, dx = 0, \tag{50}$$

$$\lim_{\mu \rightarrow +\infty} \int_{Q_T} \int_0^t F_i S''_m(u_{i,n}) \nabla u_{i,n} W_\mu^n \, ds \, dt \, dx = 0. \tag{51}$$

$$\lim_{\mu \rightarrow +\infty} \lim_{n \rightarrow +\infty} \int_{Q_T} \int_0^t \phi_{i,n}(x, t, u_{i,n}) S'_m(u_{i,n}) \nabla W_\mu^n \, ds \, dt \, dx = 0, \tag{52}$$

$$\lim_{\mu \rightarrow +\infty} \lim_{n \rightarrow +\infty} \int_{Q_T} \int_0^t S''_m(u_n) \phi_{i,n}(x, t, u_{i,n}) \nabla u_{i,n} \nabla W_\mu^n \, ds \, dt \, dx = 0. \tag{53}$$

For the proof of(52) and (53) the reader is referred to ([2]),(44) and (45) hold true. Note that, taking the limit as n tends to $+\infty$ in (41) and using (45) show that u satisfies (20). Now we want to prove that u satisfies the equation (21).

Let S be a function in $W^{2,\infty}(\mathbb{R})$ such that $\text{supp}S' \subset [-k, k]$ where k is a real positive number. Pointwise multiplication of the approximate equation (30) by $S'(u_n)$ leads to

$$\frac{\partial B_{i,S}^n(x, u_{i,n})}{\partial t} - \text{div} \left(a_n(x, t, u_{i,n}, \nabla u_{i,n}) S'(u_{i,n}) \right) + S''(u_{i,n}) a(x, t, u_{i,n}, \nabla u_{i,n}) \nabla u_{i,n} \tag{54}$$

$$+ \text{div} \left(\phi_{i,n}(x, t, u_{i,n}) S'(u_{i,n}) \right) - S''(u_{i,n}) \phi_{i,n}(x, t, u_{i,n}) \nabla u_{i,n} = f_{i,n} S'(u_{i,n})$$

$$- \text{div}(F_i S'(u_{i,n})) + S''(u_{i,n}) F_i \nabla u_{i,n} \quad \text{in } D'(Q_T),$$

where $B_{i,S}^n(x, r) = \int_0^r \frac{\partial b_{i,n}(x, s)}{\partial s} S'(s) \, ds$. In what follows we pass to the limit as n tends to $+\infty$ in each term of (54). Since the fact that $u_{i,n}$ converges to u_i a.e. in Q_T implies that $B_{i,S}^n(x, u_{i,n})$ converges to $B_{i,S}(x, u_i)$ a.e. in Q_T and $L^\infty(Q_T)$ is weak-*, we have that $\frac{\partial B_{i,S}^n(x, u_{i,n})}{\partial t}$ converges to $\frac{\partial B_{i,S}(x, u_i)}{\partial t}$ in $D'(Q_T)$. We observe that the term $a_n(x, t, u_{i,n}, \nabla u_{i,n}) S'(u_{i,n})$ can be identified with $a(x, t, T_k(u_{i,n}), \nabla T_k(u_{i,n})) S'(u_{i,n})$ for $n \geq k$, so using the pointwise convergence of $u_{i,n}$ to u_i in Q_T and the weak convergence of $T_k(u_{i,n})$ to $T_k(u_i)$ in $L^p(0, T; W_0^{1,p}(\nu))$, we get $a_n(x, t, u_{i,n}, \nabla u_{i,n}) S'(u_{i,n}) \rightharpoonup a(x, t, T_k(u_{i,n}), \nabla T_k(u_i)) S'(u_i)$ in $L^{p'}(\nu^{1-p'})$, and $S''(u_{i,n}) a_n(x, t, u_{i,n}, \nabla u_{i,n}) \nabla u_{i,n} \rightharpoonup S''(u_i) a(x, t, T_k(u_{i,n}), \nabla T_k(u_i)) \nabla T_k(u_i)$

in $L^1(Q_T)$. Furthermore, $\phi_{i,n}(x, t, u_{i,n})S'(u_{i,n}) = \phi_{i,n}(x, t, T_k(u_{i,n}))S'(u_{i,n})$ a.e. in Q_T . By (27) we obtain $|\phi_{i,n}(x, t, T_k(u_{i,n}))S'(u_{i,n})| \leq \nu(x)|c_i(x, t)|k^\gamma$, it follows that $\phi_{i,n}(x, t, T_k(u_{i,n}))S'(u_{i,n}) \rightarrow \phi_{i,n}(x, t, T_k(u_i))S'(u_i)$ strongly in $L^{p'}(\nu^{1-p'})$.

In a similar way

$$S''(u_{i,n})\phi_{i,n}(x, t, u_{i,n})\nabla u_{i,n} = S''(T_k(u_{i,n}))\phi_{i,n}(x, t, T_k(u_{i,n}))\nabla T_k(u_{i,n}) \quad \text{a.e. in } Q_T.$$

Using the weak convergence of $T_k(u_{i,n})$ in $L^p(0, T; W_0^{1,p}(\nu))$ it is possible to prove that $S''(u_{i,n})\phi_{i,n}(x, t, u_{i,n})\nabla u_{i,n} \rightarrow S''(u_i)\phi_i(x, t, u_i)\nabla u_i$ in $L^1(Q_T)$, and $S''(u_{i,n})F_i\nabla u_{i,n}$ converges to $S''(u_i)F_i\nabla u_i$ in $L^1(Q_T)$. Since $|S'(u_{i,n})| \leq C$, it follows that $F_iS''(u_{i,n})$ converges to $F_iS''(u_i)$ strongly in $L^{p'}(\nu)$. Finally by (28) we deduce that $f_nS''(u_{i,n})$ converges to $f_iS''(u_i)$ in $L^1(Q_T)$. It remains to prove that $B_{i,S}(x, u_i)$ satisfies the initial condition $B_{i,S}(x, u_i)(t = 0) = B_{i,S}(x, u_{i,0})$ in Ω . To this end, firstly note that $B_{i,S}^n(x, u_{i,n})$ is bounded in $L^p(0, T; W_0^{1,p}(\nu))$. Secondly, the above considerations of the behavior of the terms of this equation show that $\frac{\partial B_{i,S}^n(x, u_{i,n})}{\partial t}$ is bounded in $L^1(Q_T) + L^{p'}(0, T; W^{-1,p'}(\nu^{1-p'}))$. As a consequence, $B_{i,S}^n(x, u_{i,n})(t = 0) = B_{i,S}^n(x, u_{i,0n})$ converges to $B_{i,S}(x, u_i)(t = 0)$ strongly in $L^1(\Omega)$ (for the proof of this trace result see [12]). On the other hand, the smoothness of S implies that $B_{i,S}(x, u_i)(t = 0) = B_{i,S}(x, u_{i,0})$ in Ω . The proof of Theorem 3.1 is complete.

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