Nonlinear Dynamics and Systems Theory, 8 (4) (2008) 329-337



Approximate Constraint-Following of Mechanical Systems under Uncertainty

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Received: June 1, 2007; Revised: September 10, 2008

Abstract: We consider a mechanical system, which is required to obey a set of constraints. The system may contain uncertainty, which is possibly fast time-varying. We propose a robust control scheme that is motivated by the Nature's strategy. The control also takes into account the uncertainty for guaranteeing approximate constraint following.

Keywords: Mechanical system; constraint; motion control; robust control.

Mathematics Subject Classification (2000): 70Q05, 70E60, 93B52.